



ENGR 21: **Computer Engineering Fundamentals**

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Lecture 21
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Polynomial Interpolation

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Finding a straight line through 2 points is the simplest kind of polynomial interpolation

1. Write down the equation of a line

$$y = a_0 + a_1 x$$

order 1 (x_1, y_1)

line: polynomial
of first order.
 $n=1$

2. Plug in the data points

2 equations
2 points

$$\begin{cases} y_0 = a_0 + a_1 x_0 \\ y_1 = a_0 + a_1 x_1 \end{cases}$$

(x_0, y_0)

a system of equations

known: (x_i, y_i) for $i=0$
to $i=n$

unknown: (a_0, a_1)

3. Solve simultaneous equations for the two unknowns

$$\begin{bmatrix} 1 & x_0 \\ 1 & x_1 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \end{bmatrix}$$

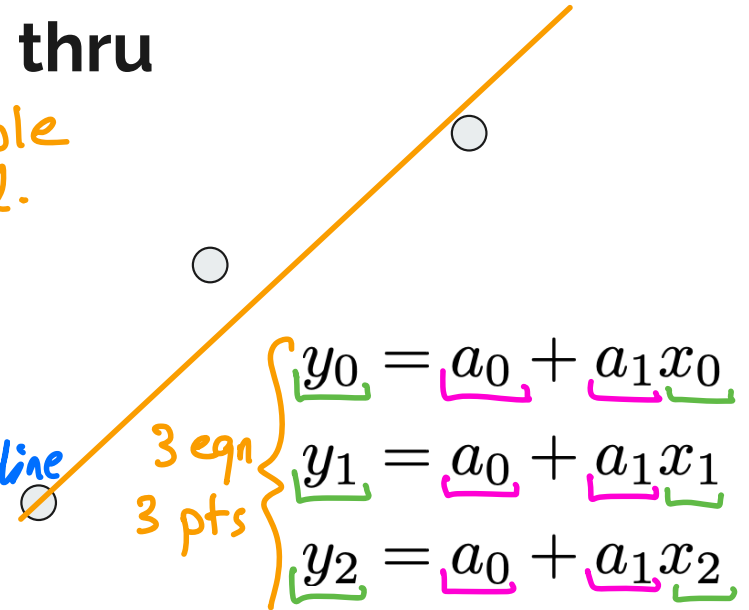
Finding a straight line that goes thru all three points

→ Not possible in general.

- Use 3 data points to attempt a straight line fit to three points.

→ Need a curve, not straight line

→ Let's use quadratic curve.



$$\begin{bmatrix} 1 & x_0 \\ 1 & x_1 \\ 1 & x_2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ y_2 \end{bmatrix}$$

Known
unknown

Finding a quadratic curve that goes thru all three points

order $n=2$

NOT close by!
exactly pass through
 (x_2, y_2)

1. Write down the equation of the curve

3 coefficients

$$y = a_0 + a_1x + a_2x^2$$

2. Plug in the data points

(x_0, y_0)

A polynomial of order 2 can "interpolate between" 3 points

knowns
unknowns

3x3 matrix
3x1 vector
3x1 vector

3. Solve simultaneous equations for the three unknowns

unknowns

$$\begin{bmatrix} 1 & x_0 & x_0^2 \\ 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ y_2 \end{bmatrix}$$

knowns

$$A \vec{x} = \vec{b}$$

matrix-vector equation can be solved with direct / iterative numerical methods.

Generalizing Polynomial Interpolation

You can (almost) always find a unique n -degree polynomial that goes through $n+1$ points using a matrix of size $(n+1) \times (n+1)$

$$\begin{bmatrix}
 1 & x_0^1 & x_0^2 & \cdots & x_0^n \\
 1 & x_1^1 & x_1^2 & \cdots & x_1^n \\
 \vdots & \vdots & \vdots & \ddots & \vdots \\
 1 & x_n^1 & x_n^2 & \cdots & x_n^n
 \end{bmatrix}
 \begin{bmatrix}
 a_0 \\
 a_1 \\
 \vdots \\
 a_n
 \end{bmatrix}
 =
 \begin{bmatrix}
 y_0 \\
 y_1 \\
 \vdots \\
 y_n
 \end{bmatrix}$$

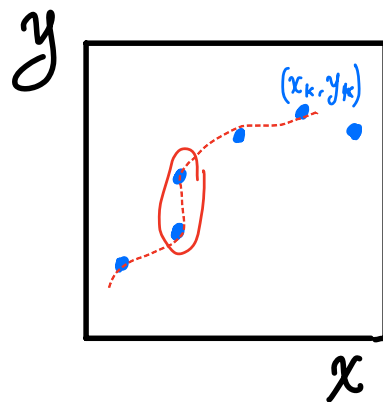
To build $y(x)$, given a_0, a_1, \dots, a_n , use `numpy.polyval`.
 Then you have a function,

$$y(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + \dots + a_nx^n$$

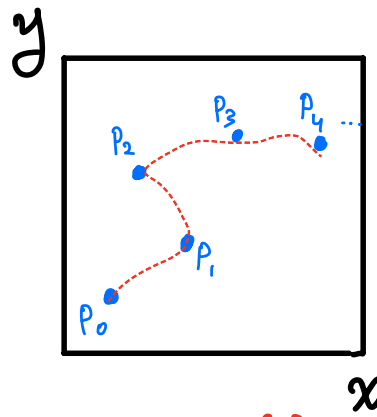
 and $y(x_k) = y_k$ for all k from 0 to n .

`numpy.linalg.solve(A, b)`
 unknowns. Solve for this

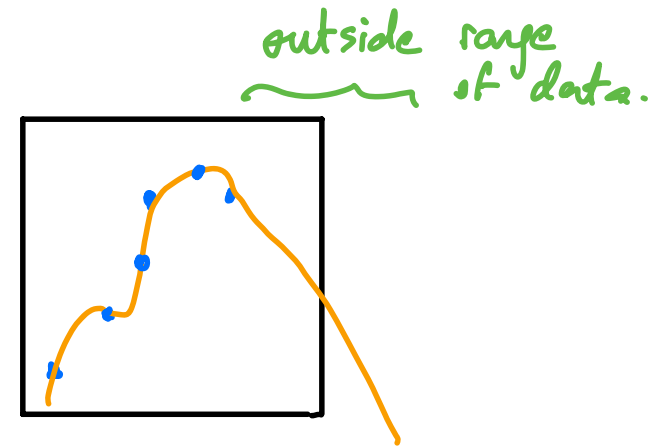
Potential Difficulties with Interpolation Matrices



function would have
to go vertical



Backtracking

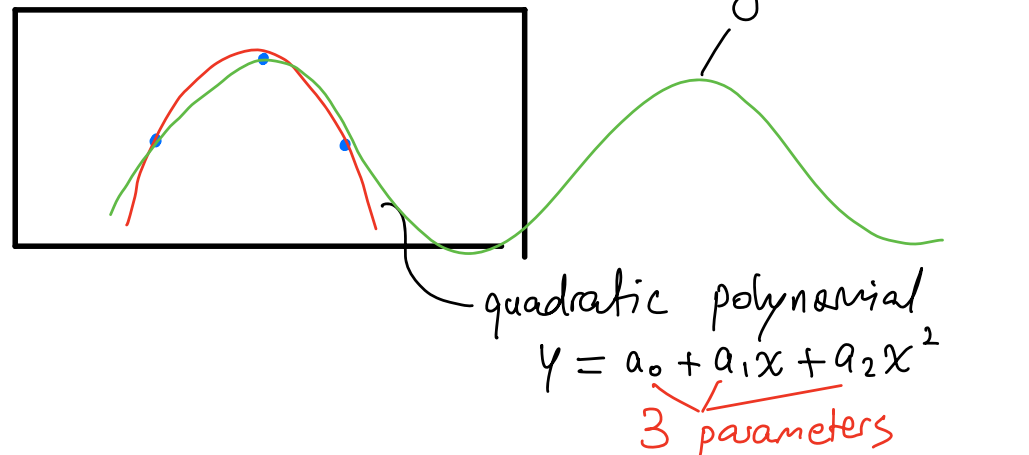


- only works in the region where you have data.
- Bad idea to extrapolate



~~Potential Difficulties with Interpolation Methods~~

→ Can also interpolate with other functions,
not necessarily polynomials.



Interpolating Matrices activity

a single line of code
that solves $A\vec{x}=\vec{b}$

- Download coordinates from course website
- Write code that:
 - Generates the interpolating matrix for these points
 - Solves a linear system for the coefficients
- How would you use these coefficients to write the interpolating function?

```
from numpy.linalg import inv as invert  
from numpy import dot
```

numpy.loadtxt

$x = \text{dot}(\text{invert}(A), b)$

x
1.0
2.0
2.5
3.0
3.5
4.5
6.0
9.0
9.5
10.0