

Mon, Apr 7 Lecture 19

Time Horizon of Prediction in systems with sensitive dependence on initial conditions.

$$\|\delta(t)\| \sim \|\delta_0\| e^{\lambda t}$$

for Lorenz system  
 $\lambda \approx 0.9$  when

$$\sigma=10, b=\frac{8}{3}, r=28$$

Find time  $t^*$  at which two initially nearby ( $\delta_0$ ) trajectories have diverged by more than  $\epsilon$ .

$$\epsilon \approx \|\delta_0\| e^{\lambda t^*}$$

$$\Rightarrow \frac{\epsilon}{\|\delta_0\|} \approx e^{\lambda t^*}$$

 $\Rightarrow$ 

$$t^* \approx \frac{1}{\lambda} \log \left[ \frac{\epsilon}{\|\delta_0\|} \right]$$

### Example

the largest Liapunov Exponent of the system.  $\approx 0.9$  for Lorenz

Two measurements were made to a precision of  $\delta_0 = 10^{-7}$

We consider deviations more than  $\epsilon = 10^{-3}$  to be unacceptable.

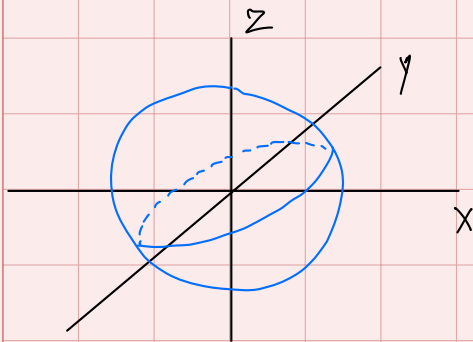
$$\Rightarrow t^* \approx 10.2 \quad \begin{matrix} \nearrow 3x \end{matrix}$$

Increase initial precision.

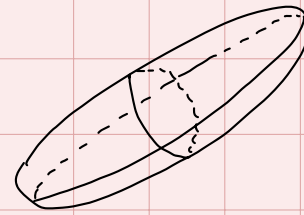
Now,  $\delta_0 = 10^{-15}$  (100,000,000 x more precise)

$$\Rightarrow t^* \approx 30.7$$

What exactly is  $\lambda$ ?



time



sphere of initial conditions  
with infinitesimal radius  $\delta$

Ellipsoid with principal  
axes

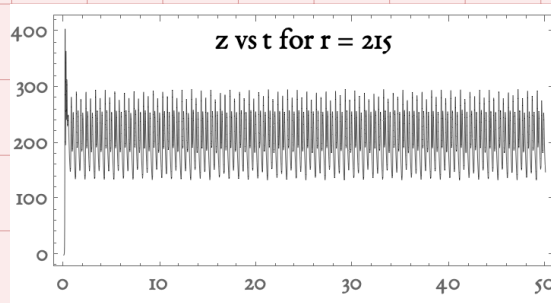
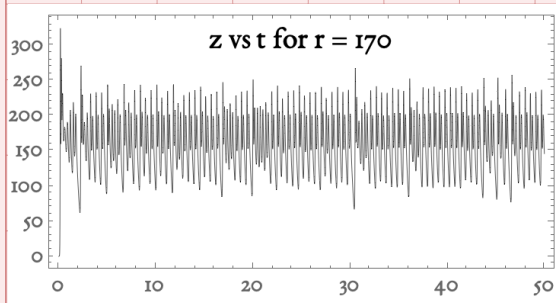
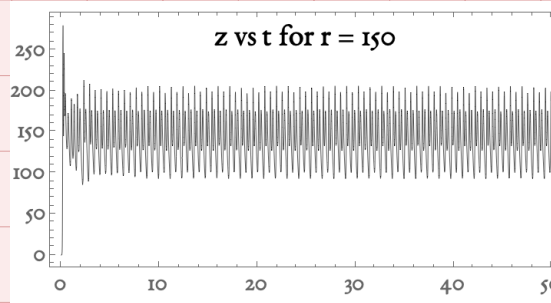
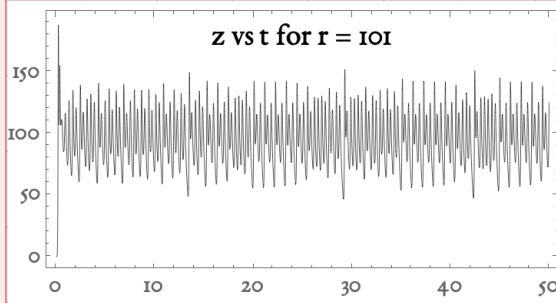
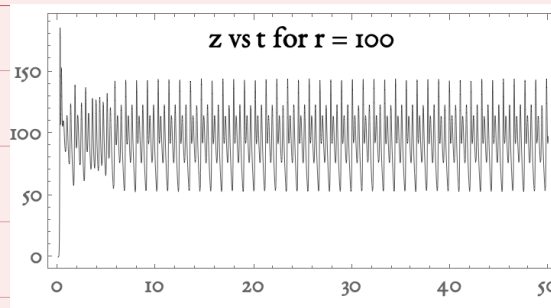
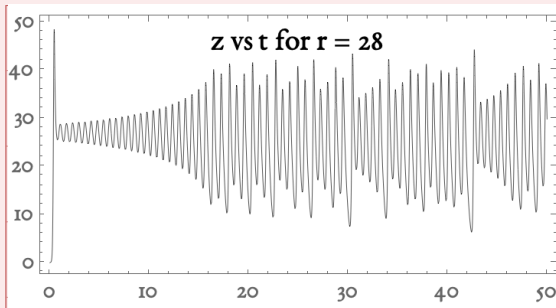
$$\begin{array}{ccc} \delta_1(0) & \longrightarrow & \delta_1(0)e^{\lambda_1 t} \\ \delta_2(0) & \longrightarrow & \delta_2(0)e^{\lambda_2 t} \\ \delta_3(0) & \longrightarrow & \delta_3(0)e^{\lambda_3 t} \end{array}$$

At large times, the largest  $\lambda_k$  controls the size of the ellipsoid.  
Liapunov Exponent.

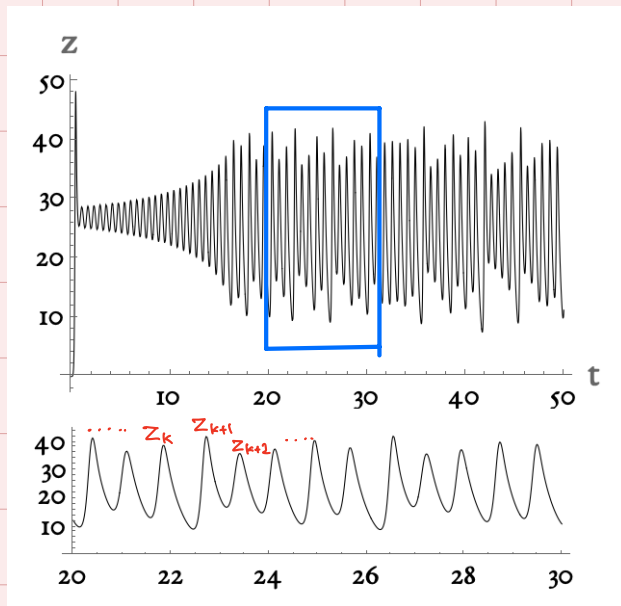
Negative  $\lambda_k \Rightarrow$  that direction shrinks  
Positive  $\lambda_k \Rightarrow$  that direction expands.

If Liapunov Exponent  $> 0$ ,  $\Rightarrow$  sensitive dependence on initial conditions.

[tinyurl.com/E91lorenz4](https://tinyurl.com/E91lorenz4)  $\longrightarrow$  remix



order  $\longrightarrow$  chaos  $\longrightarrow$  order  $\longrightarrow$  chaos  $\longrightarrow$  ?



Continuous Time

Differential Eqs

Discrete Time

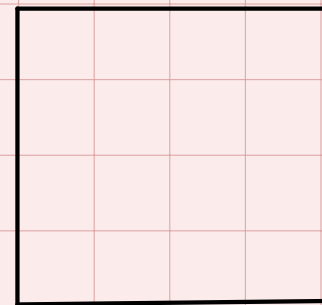
Maps

$$\dot{x} = f(x)$$

$$x_{n+1} = f(x_n)$$

These two are not the same, even if you have a "map" and a differential eqn. describing the same underlying system.

If you know "f" for a map, you can plot  $\rightarrow z_{n+1}$  by graphing the function.



For Lorenz system, you have to do this empirically

